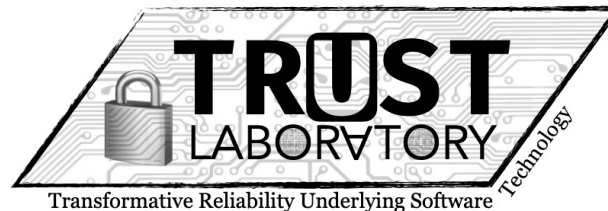


(Nearest) Neighbors You Can Rely On

Formally Verified k -d Tree Construction and Search in Coq

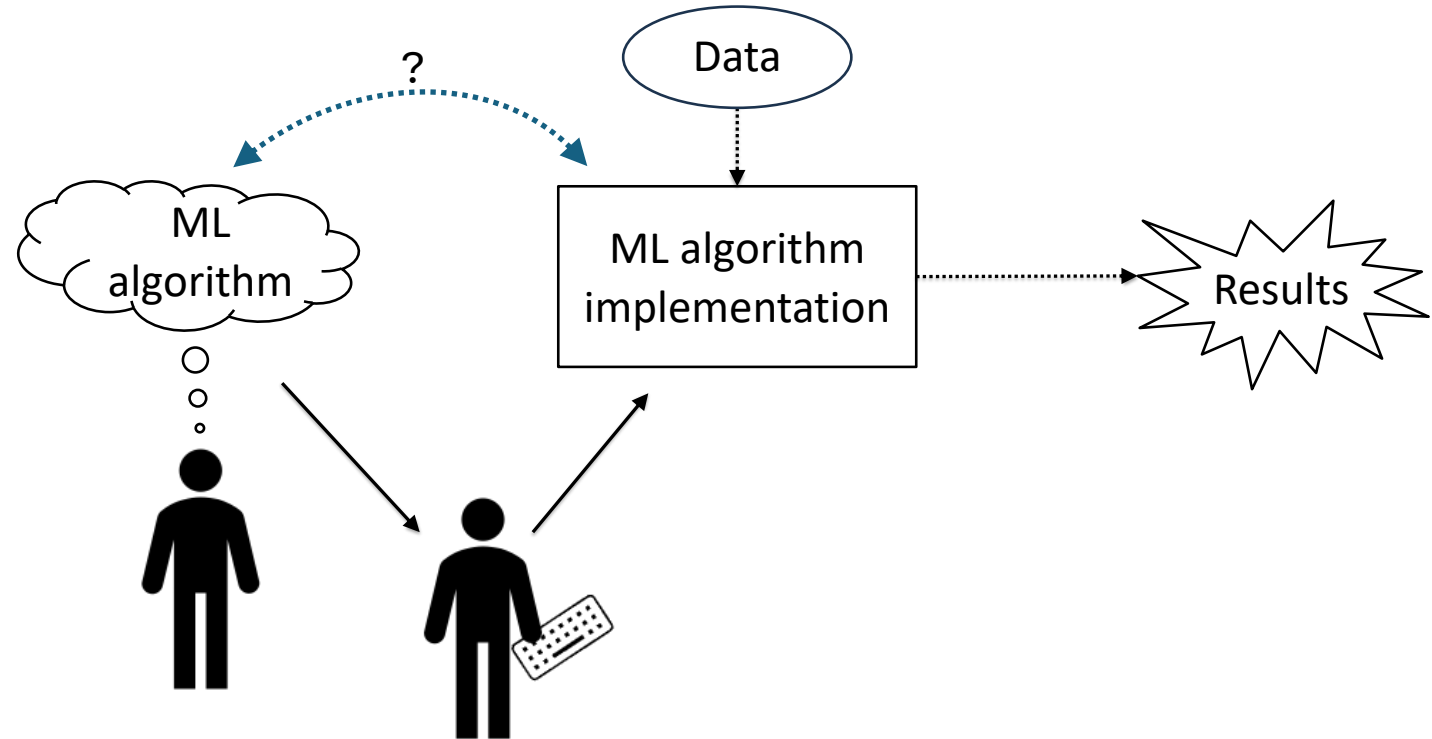
Nadeem Abdul Hamid
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SAC-SVT 2024, Ávila, Spain

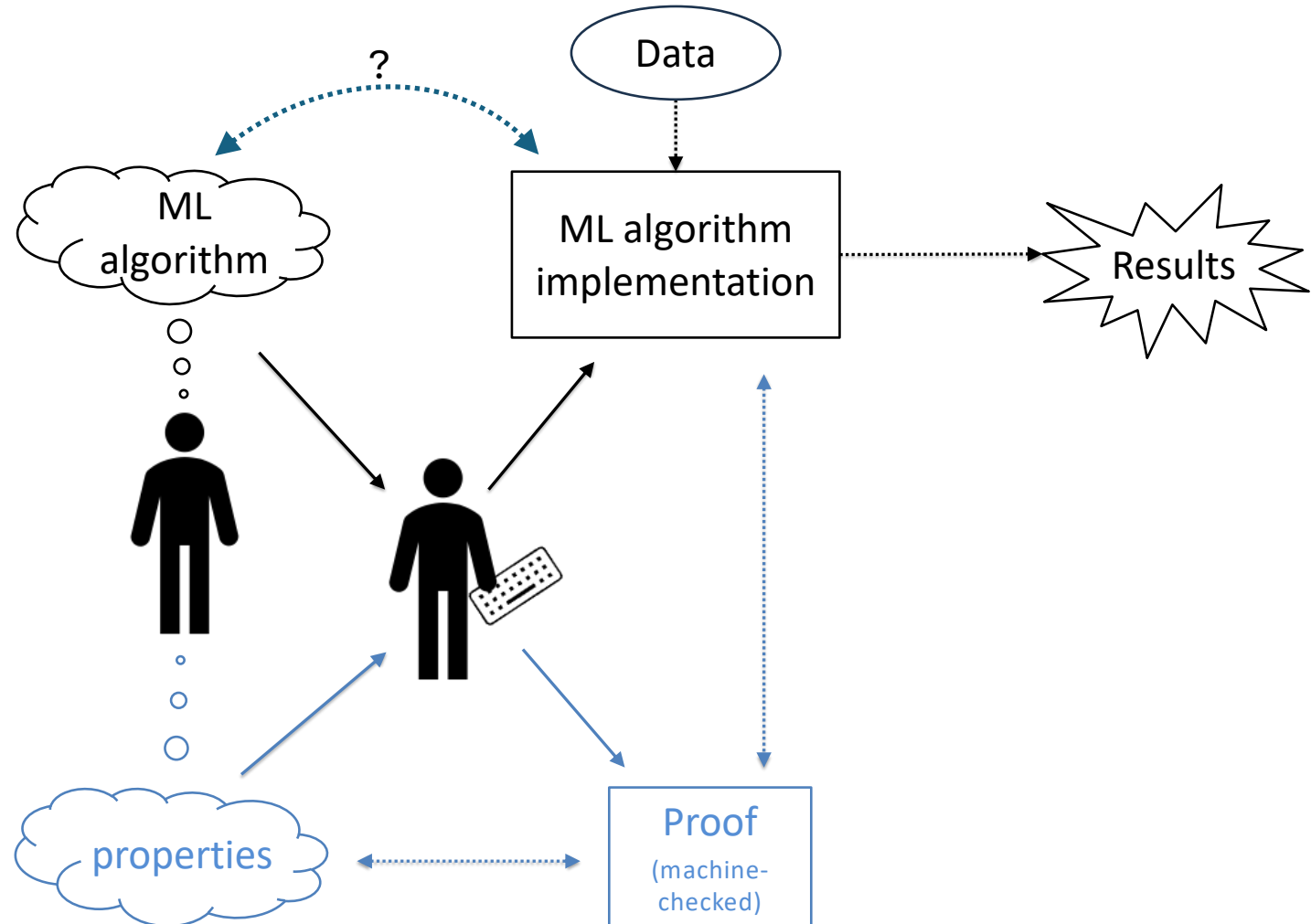
Implementing Machine Learning Algorithms

- Gap between the mathematical model and mechanics of implementation



Implementing Machine Learning Algorithms

- Gap between the mathematical model and mechanics of implementation
- (Big Picture) Context for this work: *Development of verified implementations of ML systems*



Focus: KNN (*K-nearest-neighbors*) Search

- Does the program code for an ML algorithm faithfully implement the mathematical description?
- Focus on the mechanics of the algorithm, not meta-theoretical properties
 - That an implementation correctly finds the closest neighbors to a query
 - Not that those closest neighbors have some statistical properties (Future work)

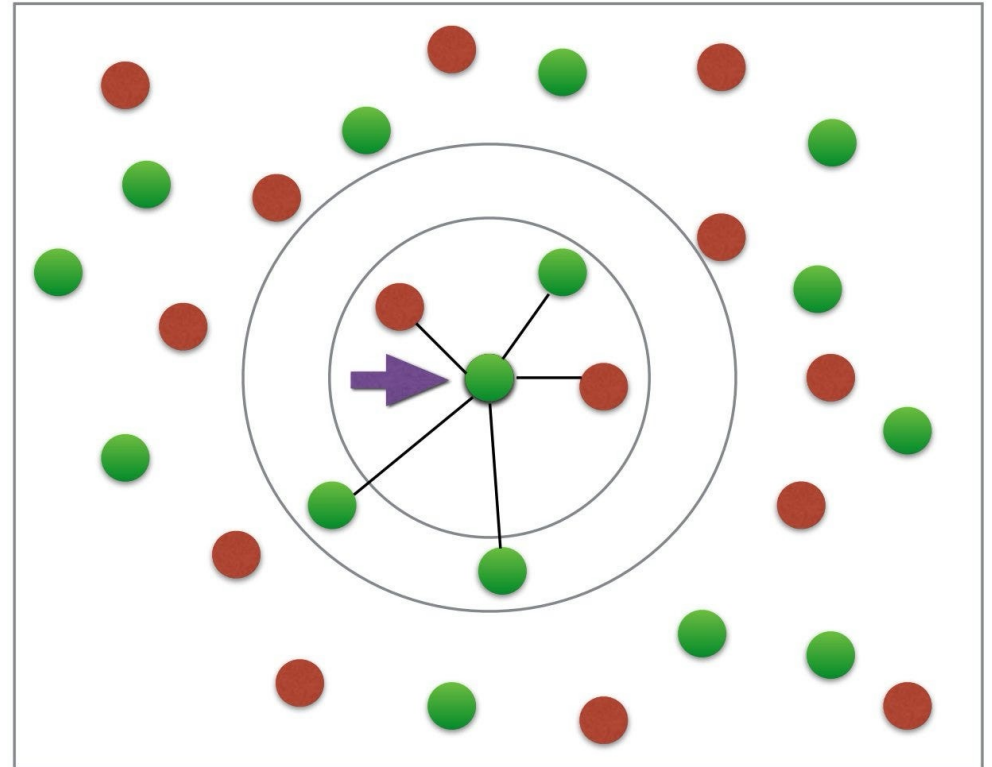
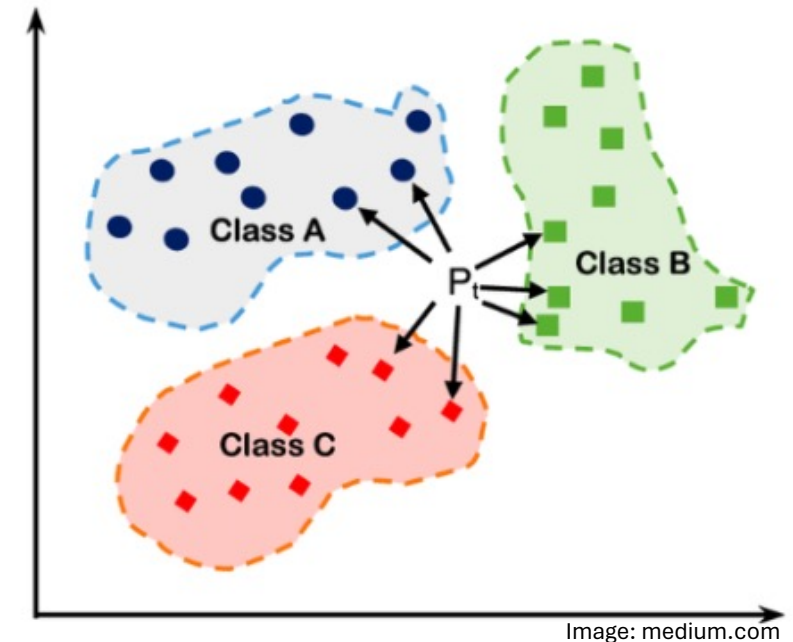


Image: datacamp.com

KNN Search

- One of the oldest, well-known, widely used classification algorithms
 - Assigns class labels to observations based on previously seen data
 - Can also be used for regression
- Applied in a wide variety of domains (not just ML)
- Popularity can be attributed to its simplicity, ease of implementation, and high accuracy rates
- Although, there are known limitations of KNN search
 - (curse of dimensionality; scaling to large data sets)



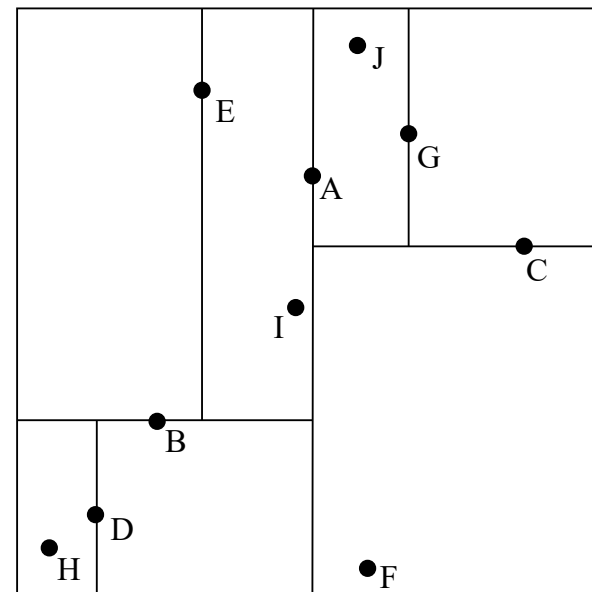
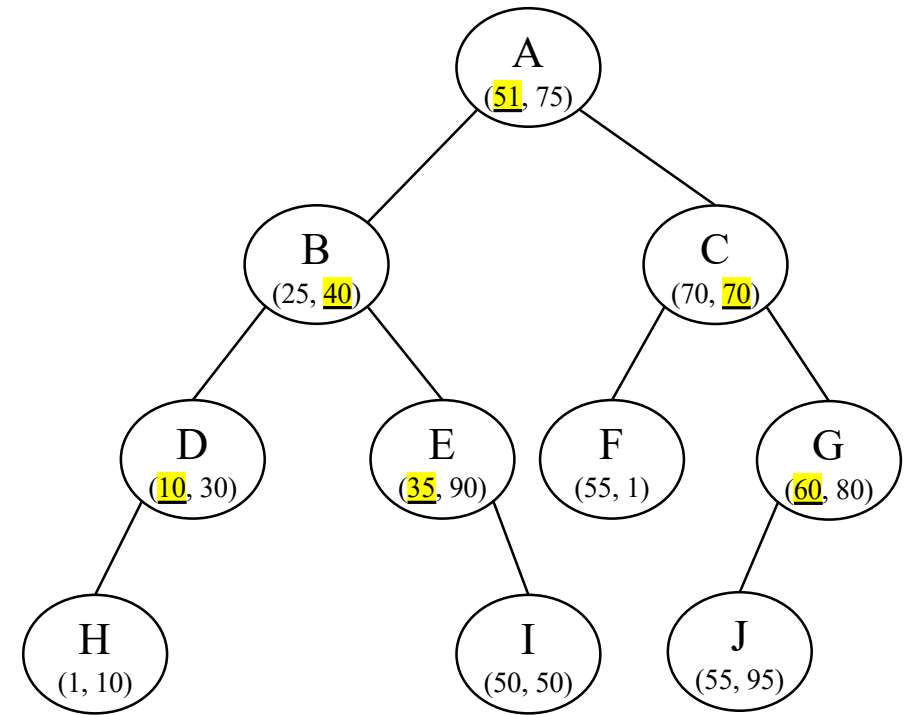
Our Results

Formally verified (machine-checkable) implementation of a **KNN search algorithm** in the **Coq proof assistant**

- Implementing/Integrating previously-verified data structures
 - ***k-d trees*** (new)
 - bounded priority queue (adapted)
- And algorithms
 - **Quick-select** median finding
 - Generalized ***K-nearest neighbors search***

k-d trees

- Binary tree
- Nodes: *k*-dimensional data points
- Each level partitioned based on one of *k* dimensions
- Each subtree associated with an (implicit) bounding box
- Enables sub-linear NN search complexity through branch-and-bound



I: (50, 50)
A: (51, 75)
B: (25, 40)
C: (70, 70)
J: (55, 95)
H: (1, 10)
G: (60, 80)
F: (55, 1)
E: (35, 90)
D: (10, 30)

Lowercase *k* = dimension of data points;
Uppercase *K* = number of neighbors

Bounding boxes

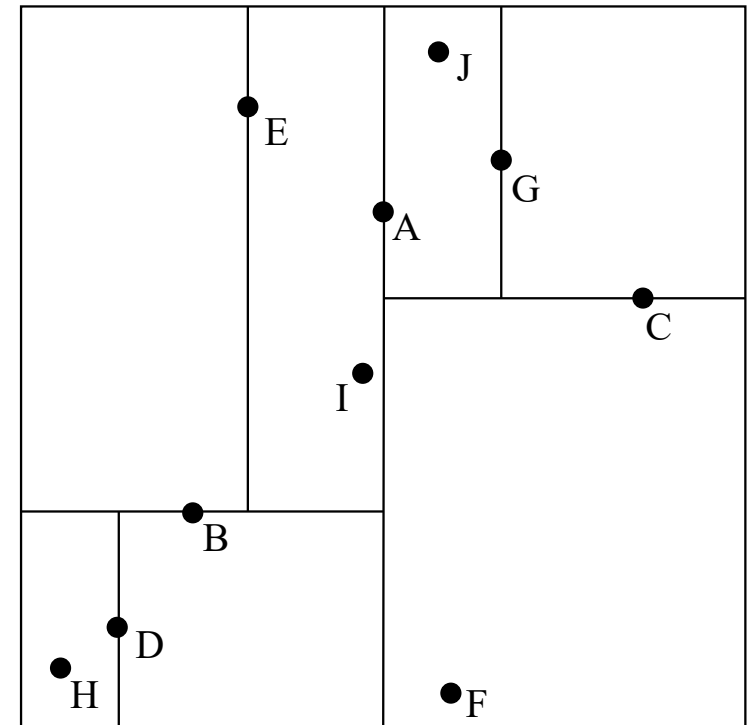
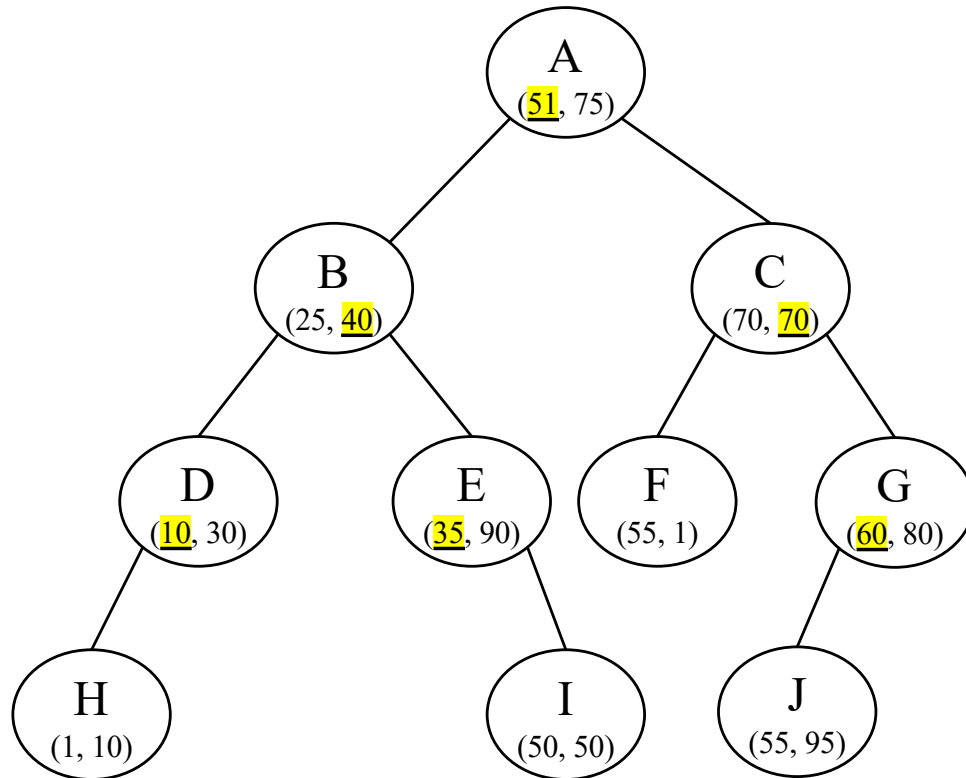
- Implicit in implementation;
Crucial to correctness

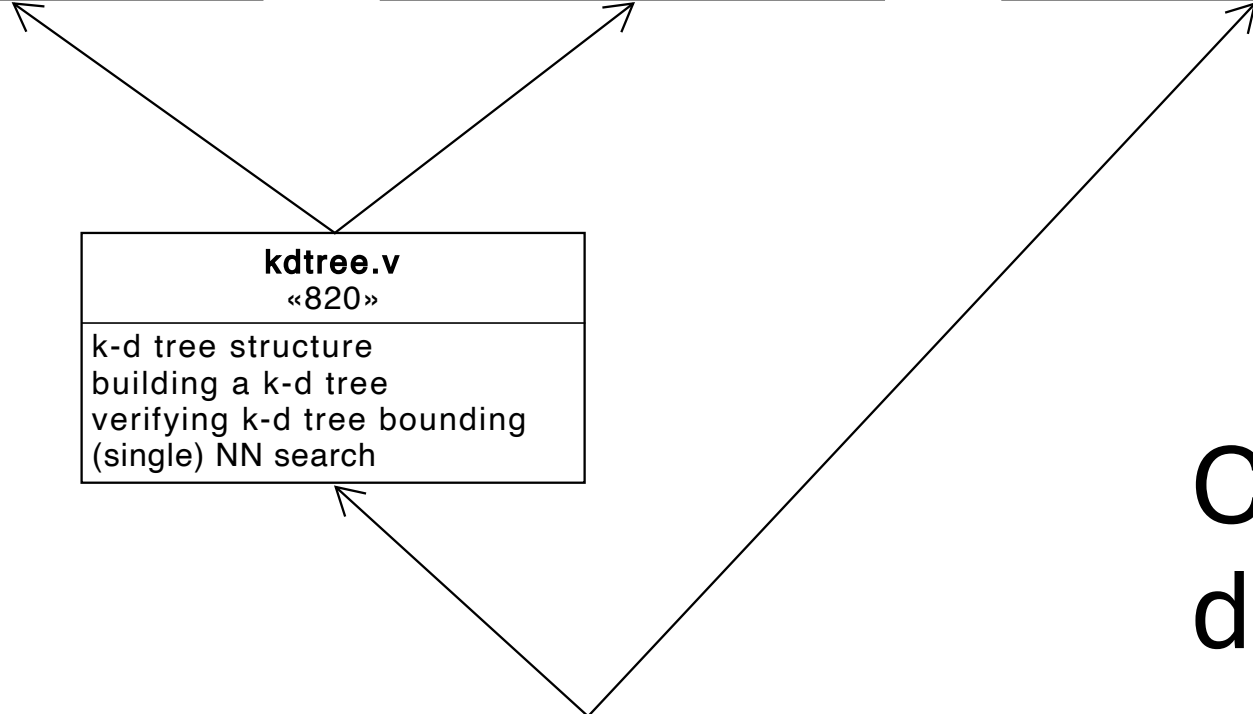
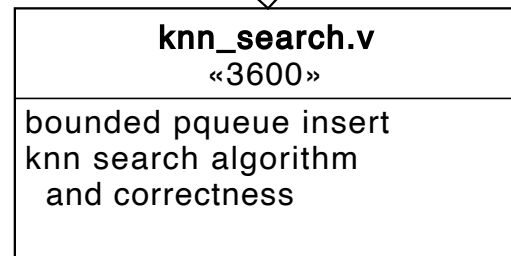
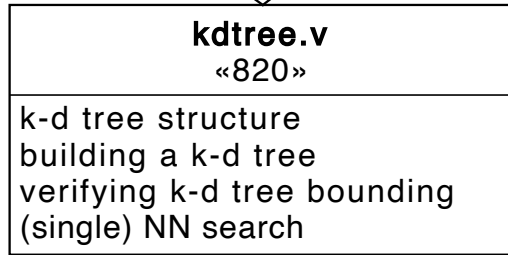
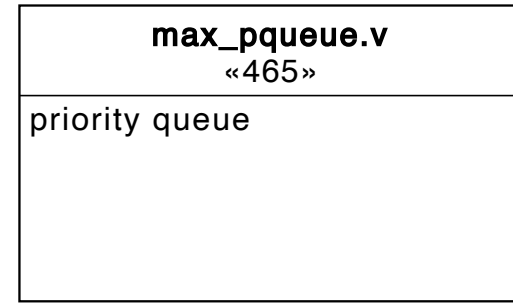
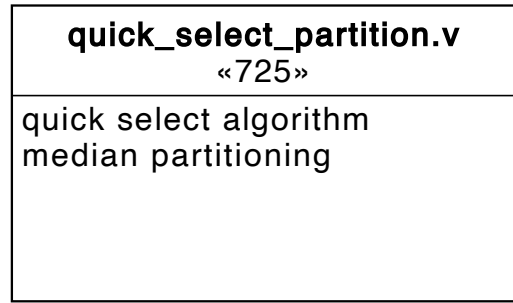
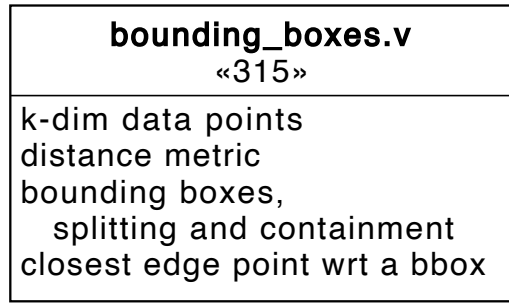
$$[(x_{\min}, y_{\min}), (x_{\max}, y_{\max})]$$

$$A - [(-\infty, -\infty), (+\infty, +\infty)]$$

...

$$I - [(35, 40), (51, +\infty)]$$



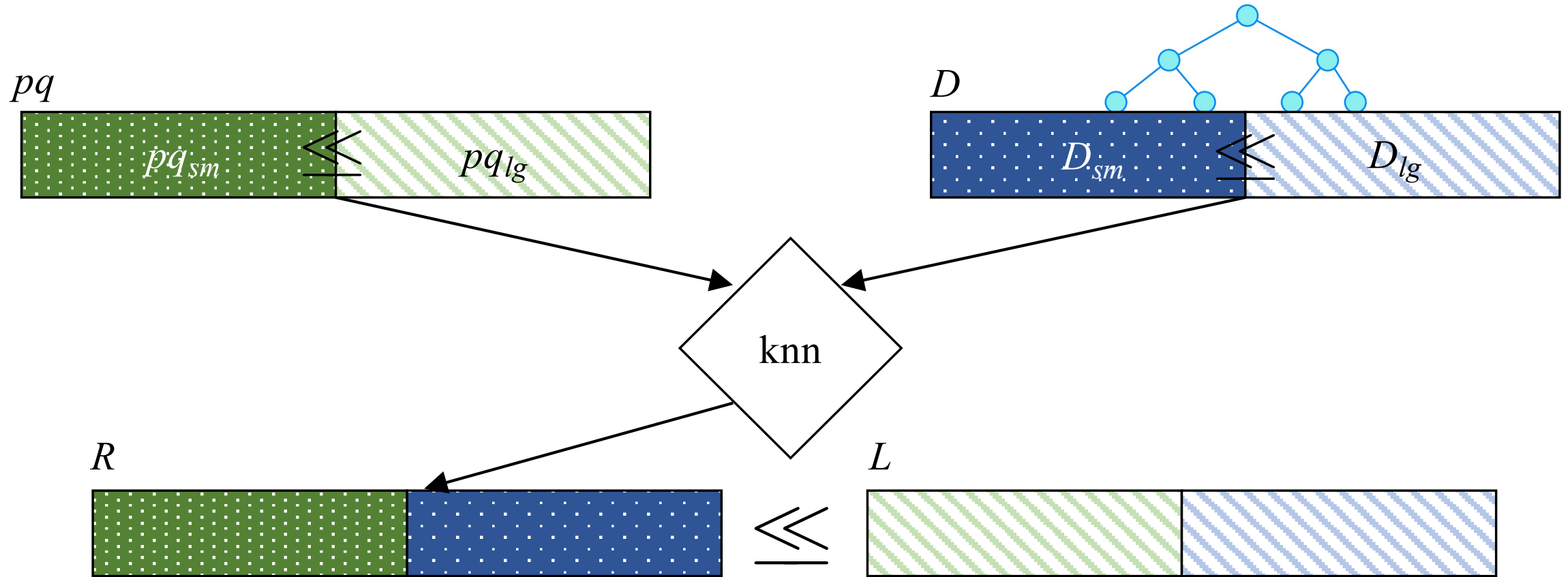


Coq
developments

Final Theorem

```
Theorem knn_search_build_kdtree_correct :  
  forall (K:nat) (k : nat) (data : list datapt), // Preconditions:  
    0 < K -> // at least one neighbor sought  
    0 < length data -> // data is non-empty  
    0 < k -> // dimension space is non-empty  
    (forall v' : datapt,  
      In v' data -> length v' = k) -> // all data points well-formed (k-dim)  
  forall tree query result,  
    tree = (build_kdtree k data) -> // If: the k-d tree built from data  
    knn_search K k tree query = result -> // produces result for a query point,  
    exists leftover, // Then:  
      length result = min K (length data) // the result is length (at most) K,  
      /\ Permutation data (result ++ leftover) // and is a sub-list of data,  
      /\ all_in_leb (sum_dist query) result leftover. // and everything in  
        // result is closer in distance to the query than all the leftover part of data.
```

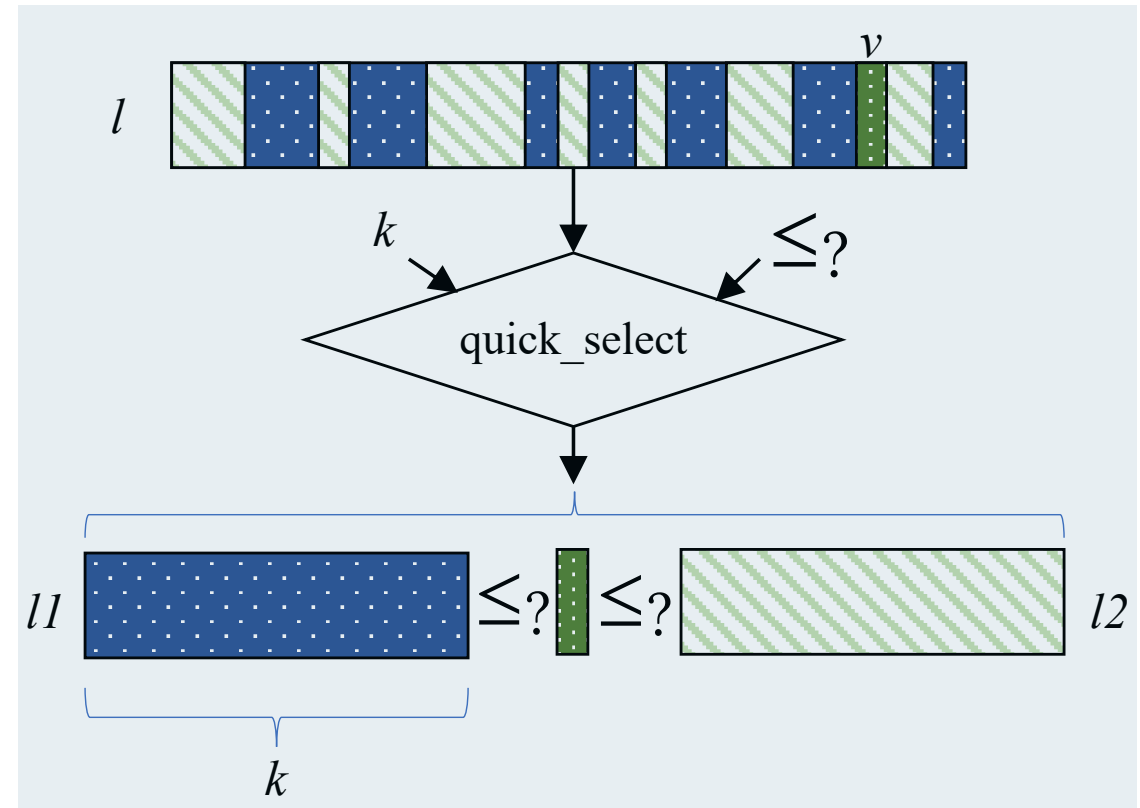
Partitions Induced by the *knn* Function



Quickselect

- Used to build the initial k -d tree

```
Theorem quick_select_exists_correct :  
  forall (X:Set) (k:nat) (l:list X)  
    (le:X -> X -> bool),  
  le_props le ->  
  k < length l ->  
  exists l1 v l2,  
    quick_select k l le = Some (l1,v,l2) /\  
    Permutation l (l1 ++ v :: l2) /\  
    length l1 = k /\  
    (forall x, In x l1 -> le x v = true) /\  
    (forall x, In x l2 -> le v x = true).
```



Future Work

- ~~Abstract the distance metric~~
- *Automate permutations reasoning*
- *Implement, specify, & verify a KNN-based classification algorithm*

- Port to verified C implementation
- Extend to modern variants of KNN (e.g. approximation, etc.)

Acknowledgements

Matthew Bowker

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Thank you!

Questions?

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```

Fixpoint knn (K:nat) (k:nat) (tree:kdtree) (bb:bbox) (query:datapt)
  (pq:priqueue datapt (sum_dist query)) : priqueue datapt (sum_dist query)
:= match tree with
| mt_tree => pq
| node ax pt lft rgt =>
  let body (pq':priqueue datapt (sum_dist query)) :=
    let dx := nth ax pt 0 in
    let bbs := bb_split bb ax dx in
    if (ith_leb ax pt query)
    then (knn K k rgt (snd bbs) query (knn K k lft (fst bbs) query pq'))
    else (knn K k lft (fst bbs) query (knn K k rgt (snd bbs) query pq'))
  in
  match (peek_max _ _ pq) with
  | None => body (insert_bounded K _ _ pt pq)
  | Some top => if (K <=? (size _ _ pq))
    && ((sum_dist query top) <?
      (sum_dist query (closest_edge_point query bb)))
    then pq
    else body (insert_bounded K _ _ pt pq)
  end
end.

```

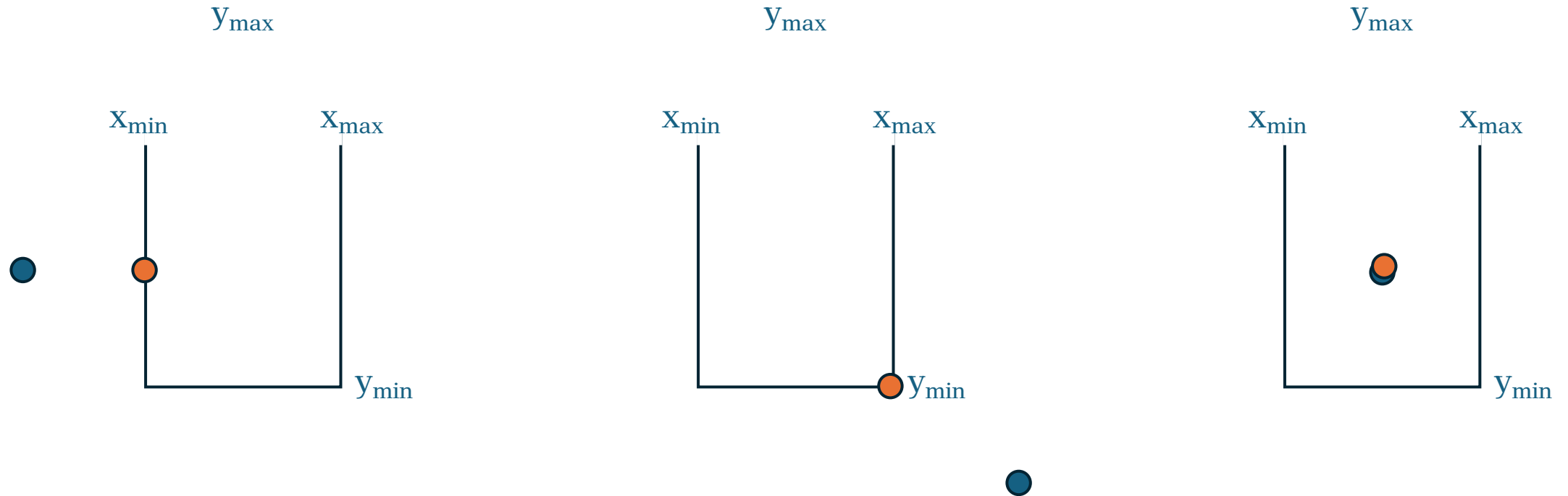


```
Definition knn_search (K:nat) (k:nat) (tree:kdtree) (query:datapt) : list datapt
:=
pq_to_list
  (knn K k tree (mk_bbox (repeat None k) (repeat None k))
   query
   (empty datapt (sum_dist query))).
```

Closest Enclosed Point (cep)

LEMMA 4.6 (CEP_MIN_DIST).

Given a point q and bounding box B , $\forall p \in B, \delta_q(\text{cep}(q, B)) \leq \delta_q(p)$.



```

Definition insert_bounded (K:nat) A key (e:A) (pq:priqueue A key)
                                     : priqueue A key :=
  let updpq := (insert A key e pq)
  in
    if K <? (size A key updpq) then
      match delete_max _ key updpq with
      | None => updpq (* should never happen *)
      | Some (_, updpq') => updpq'
    end
  else updpq.

```

```

Lemma insert_bounded_preserve_max
  : forall (K : nat) (A : Type) (key : A -> nat) (e : A)
    (pq : priqueue A key) (lst : list A),
  priq A key pq ->
  Abs A key pq lst ->
  size A key pq = K -> size A key (insert_bounded K A key e pq) = K.

```

Proof.

```
unfold insert_bounded; intros.
rewrite insert_size with (a1:=lst); auto.
rewrite HK.
replace (K <? 1 + K) with true.
2: { destruct (K <? 1 + K) eqn:Hk; auto; split_andb_leb; lia. }
pose proof (insert_delete_max_some _ _ e _ _ Hpriq Habs) as (k, (q, Hd)).
rewrite Hd.
apply delete_max_Some_size with (p:=(insert A key e pq)) (k:=k) (pl:=e::lst)
; auto.
rewrite <- HK.
eapply insert_size; eauto.
```

Qed.

```

insert_bounded_preserve_max =
(fun (K : nat) (A : Type) (key : A -
> nat) (e : A) (pq : priqueue A key) (lst : list A) (Hpriq : priq A key pq) (Habs : Abs A key pq lst) (HK : size A key pq = K) => eq_ind_r (fun n : nat => size A key (i
f K <? n then match delete_max A key (insert A key e pq) with
| Some (_, updpq') => updpq'
| None => insert A key e pq
end else insert A key e pq) = K) (eq_ind_r (fun n : nat => size A key (if K <? 1 + n then match delete_max A key (insert A key e pq) with
| Some (_, updpq') => updpq'
| None => insert A key e pq
end else insert A key e pq) = K) (let H : true = (K <? 1 + K) := let b := K <? 1 + K in let Hk : (K <? 1 + K) = b := eq_refl in (if b as b0 return ((K <? 1 + K) = b0 -
> true = b0) then fun _ : (K <? 1 + K) = true => eq_refl else fun Hk0 : (K <? 1 + K) = false => let H : forall x y : nat, (x <? y) = false -
> y <= x := fun x y : nat => match Nat.ltb_ge x y with
| conj x0 _ => x0
end in let Hk1 : 1 + K <= K := H K (1 + K) Hk0 in let Hk2 : BinInt.Z.le (BinInt.Z.add (BinNums.Zpos BinNums.xH) (BinInt.Z.of_nat K)) (BinInt.Z.of_nat K) := ZifyClasses.
rew_iff (1 + K <= K) (BinInt.Z.le (BinInt.Z.add (BinNums.Zpos BinNums.xH) (BinInt.Z.of_nat K)) (BinInt.Z.of_nat K)) (ZifyClasses.mkrel nat BinNums.Z le BinInt.Z.of_nat
BinInt.Z.le Znat.Nat2Z.inj_le (1 + K) (BinInt.Z.add (BinNums.Zpos BinNums.xH) (BinInt.Z.of_nat K)) (ZifyClasses.mkapp2 nat nat BinNums.Z BinNums.Z BinNums.Z Nat.add
BinInt.Z.of_nat BinInt.Z.of_nat BinInt.Z.of_nat BinInt.Z.add Znat.Nat2Z.inj_add 1 (BinNums.Zpos BinNums.xH) eq_refl K (BinInt.Z.of_nat K) eq_refl) K (BinInt.Z.of_nat K
) eq_refl) Hk1 in let HK0 : BinInt.Z.of_nat (size A key pq) = BinInt.Z.of_nat K := ZifyClasses.rew_iff (size A key pq = K) (BinInt.Z.of_nat (size A key pq) = BinInt.Z.o
f_nat K) (ZifyClasses.mkrel nat BinNums.Z eq BinInt.Z.of_nat eq (fun x y : nat => iff_sym (Znat.Nat2Z.inj_iff x y)) (size A key pq) (BinInt.Z.of_nat (size A key pq)) eq
_refl K (BinInt.Z.of_nat K) eq_refl) HK in let cstr : BinInt.Z.le BinNums.Z0 (BinInt.Z.of_nat (size A key pq)) := Znat.Nat2Z.is_nonneg (size A key pq) in let cstr0 : Bi
nInt.Z.le BinNums.Z0 (BinInt.Z.of_nat K) := Znat.Nat2Z.is_nonneg K in let __arith : forall (__p1 : Prop) (__x1 : BinNums.Z), BinInt.Z.le (BinInt.Z.add (BinNums.Zpos Bin
Nums.xH) __x1) __x1 -
> __p1 := fun (__p1 : Prop) (__x1 : BinNums.Z) => let __wit := [] in let __varmap := VarMap.Elt __x1 in let __ff := Tauto.IMPL (Tauto.A Tauto.isProp {} RingMicromega.Fl
hs := EnvRing.PEadd (EnvRing.PEc (BinNums.Zpos BinNums.xH)) (EnvRing.PEX BinNums.xH); RingMicromega.Fop := RingMicromega.OpLe; RingMicromega.Frhs := EnvRing.PEX BinNums
.xH }) tt) None (Tauto.X Tauto.isProp __p1) in ZMicromega.ZTautoChecker_sound __ff __wit (eq_refl <: ZMicromega.ZTautoChecker __ff __wit = true) (VarMap.find BinNums.Z0
__varmap) in __arith (true = false) (BinInt.Z.of_nat K) Hk2) Hk in eq_ind true (fun b : bool => size A key (if b then match delete_max A key (insert A key e pq) with
| Some (_, updpq') => updpq'
| None => insert A key e pq
end else insert A key e pq) = K) (let H0 : exists (k : A) (q : priqueue A key), delete_max A key (insert A key e pq) = Some (k, q) := insert_delete_max_some A key e pq
lst Hpriq Habs in match H0 with
| ex_intro _ x x0 => (fun (k : A) (H1 : exists q : priqueue A key, delete_max A key (insert A key e pq) = Some (k, q)) => match H1 with
| ex_intro _ x1 x2 => (fun (q : priqueue A key) (Hd : delete_max A key (insert A key e pq) = Some (k, q)) => eq_ind_r (fun o : option (A * priqueue A key) => size A key
match o with
| Some (_, updpq') => updpq'
| None => insert A key e pq
end = K) (delete_max_Some_size A key K (insert A key e pq) q k (e :: lst) lst (insert_priq A key e pq Hpriq) (insert_relate A key pq lst e Hpriq Habs) (eq_ind (size A k
ey pq) (fun K0 : nat => size A key (insert A key e pq) = S K0) (insert_size A key pq lst e Hpriq Habs) K HK) Hd) Hd) x1 x2
end) x x0
end) (K <? 1 + K) H) HK) (insert_size A key pq lst e Hpriq Habs)) : forall (K : nat) (A : Type) (key : A -
> nat) (e : A) (pq : priqueue A key) (lst : list A), priq A key pq -> Abs A key pq lst -> size A key pq = K -> size A key (insert_bounded K A key e pq) = K
: forall (K : nat) (A : Type) (key : A -> nat) (e : A) (pq : priqueue A key) (lst : list A), priq A key pq -> Abs A key pq lst -> size A key pq = K -
> size A key (insert_bounded K A key e pq) = K

```